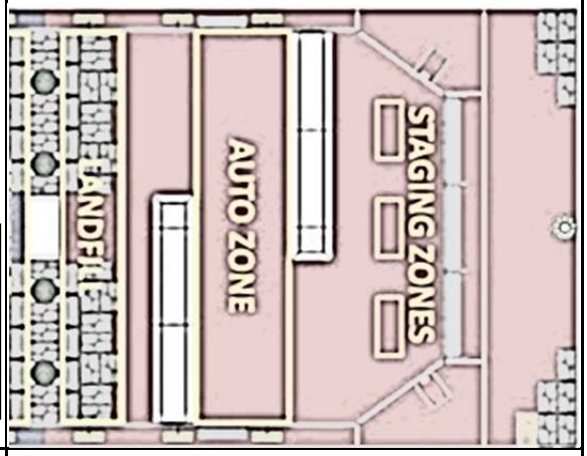
T Tote
R Recycling container
L Litter

Team:

Autonomous Notes:

Tele-op/HP Notes:



Time Remaining

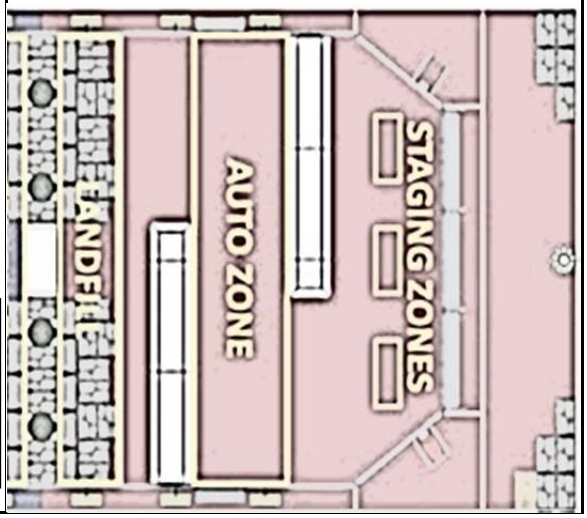
O Auto starting position
X Auto end position
- - - Auto robot movement
----- Teleop robot movement
Δ Litter

T Tote
R Recycling container
L Litter

Team:

Autonomous Notes:

Tele-op/HP Notes:



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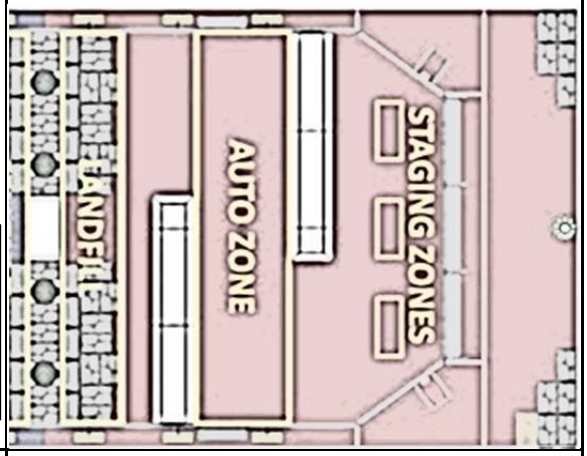

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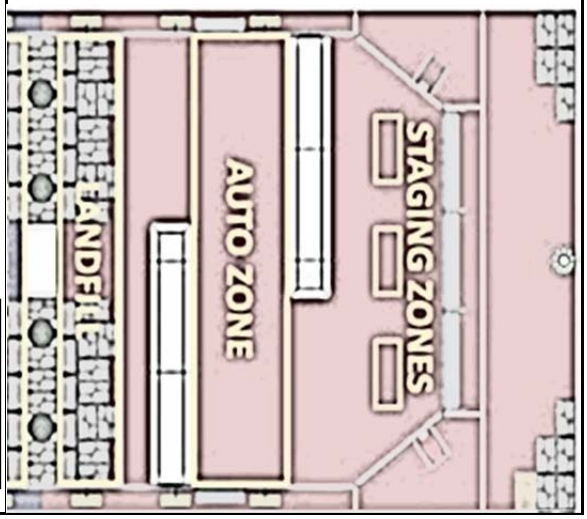
Tele-op/HP Notes: